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Motivation / Background



Key Question / Hypothesis

- Human-Machine Interaction (HMI) Principles can be applied to
 - **Retrofit an existing Freight Planning System, and**
 - Improve the Joint Cognitive System's cost and efficiency

Relevant Literature

Badreddin, E., & Wagner, A. (2011). Real-Time Level of Autonomy Adaptation for Human-Machine-Interaction Based on the Reaction Time. **IFAC Proceedings Volumes.**

Miller, C. A. (2018). Displaced Interactions in Human-Automation Relationships: Transparency over Time. *Engineering Psychology and* Cognitive Ergonomics.

Poklukar, Š., Papa, G., & Novak, F. (2017). A formal framework of humanmachine interaction in proactive maintenance - MANTIS experience. Automatika: Journal for Control, Measurement, Electronics, Computing & Communications.

Human-Machine Interaction Design for Freight Planning Systems



What does Human-**Machine Interaction (HMI)** design have in common with a common pallet?

The Problem



Methodology

- **Systems Evaluation**
 - Map 3 Automated Systems
 - Map Manual System
 - ID Automated Drops
 - **ID Human Interventions**
- **Data Collection**
- Data Analysis
- HMI Iterative Design Process
- **Retrofit Existing System**



Scenario Modeling





January 2019 Poster Session

Initial Conditions Manual Planning Costs > Automated Planning Costs by 35% Manual v. Auto (Average Cost Per Unit) \$1.00 \$0.89 \$0.85 \$0.87 \$0.89 \$ \$0.95 \$0.86 \$0.84 \$0.86 \$0.82 \$0.84 \$0.85 \$0.90 \$0.85 \$0.80 \$0.64 \$0.63 \$0.64 \$0.64 \$0.64 \$0.64 \$0.64 \$0.64 \$0.66 \$0.67 \$0.69 \$0.75 \$0.70 \$0.65 \$0.60 \$0.55 \$0.50 Octobe wembe ecembe Janual's cebrual' —— Manual Plan ACPU —— Auto Plan ACPU **Expected Contributions Practical Contributions to Company: Reduce Manual Interventions Reduce Overall Cost Increase Strategic Focus of Human Planners**

Retrofit System for Iterative Continual Improvement

Research Contributions:

- Apply HMI principles to a Novel Application
 - Freight Planning System
 - Loosely Coupled Joint Cognitive System
- **Retrofit HMI Solution to Existing System**
- **Existing High Volume Freight Planning System**
- Model for Other Joint Cognitive Systems

Task Batching

Recursive Nested

Behavior-Based

Control

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